### **TUM ABM Symposium**



## Enhancing ADAPTS/POLARIS Agent-Based Transportation System Simulation Framework



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ADAPTS/POLARIS implements an agent-based activity-travel demand framework using variety of statistical/behavioral models

- ADAPTS models dynamic activity-travel engagement:
  - Generation: deciding what needs to be done on a given day
    - Activities are generated continuously on-the fly
    - Based on needs growth over time, household requirements, mandatory acts...
  - Planning: determining the who/where/why/when/how of activity episodes
    - Attribute choices made dynamically and updated throughout the simulation
    - Dependent on the order / priority in which activities are planned
  - Scheduling: maintaining a consistent daily activity-travel plan
    - Order in which activities are planned and executed is reflected
    - Activities (including travel, work, charging...) compete for time resources
    - Intra-person, intra-household, resource scheduling, all accounted for
  - Execution: moving from planning to physical moves on the simulated network
    - Continuous integration with multi-modal network model
    - An agent-based execution persistent agents moving through networks based on their individual choices.

ADAPTS/POLARIS, initiated by UIC TransLab, has been further developed by Argonne National Lab to address key research questions

#### • Originally proposed:

- 1. Flexible activity planning/scheduling
- 2. Improve model integration / Enhance Interoperability among existing tools
- 3. Model technology / ITS Systems for planning applications

#### Core Goals of the Effort:

- Modeling Standards and Protocols
- Open Source Modeling Environment
- Listen to the Transportation Community
- Common Modeling Language
- Maintain Flexibility and Modularity

#### FTA funding to:

- 1. Understand transit rider behavior and response to disruptions
- 2. Develop system short-term forecasting tools from big data sources
- 3. Simulation for transit planning and response and recovery to emergencies

#### Multi-modal

- Freight and logistics
- Ridesharing, car-sharing
- Enhanced bus service
- Bike-sharing
- Intermodal travel
- Modal energy use

#### **Vehicles and Infrastructure**

- Refueling infrastructure
- Traffic management center
- Connected signals
- Bike-share stations
- Bike and walk lanes



#### Connectivity and Automation

- Autonomous vehicles / fleets
- ACC / CACC
- Transit signal priority
- Eco-approach / departure
- Traveler information
- Impacts of level 3/4/5 automation

#### **Urban Science**

- Data collection from vehicles and infrastructure
- Supporting future growth plans
- Land use

#### **Decision science**

- Understanding mode choice behavior
- Providing useful information to travelers
- Incentivizing energy efficiency
- Increasing 'choice' ridership
- CAV impact on behavior

### Transportation Systems Simulator Design...



### **POLARIS Workflow**

### • Key modeling features:

- Full-featured activity-based model
- Integrated demand, network assignment and traffic flow
- Includes freight shipments and local deliveries
- High-fidelity **vehicle energy** consumption
- EV charging and grid integration
- Connection to UrbanSIM land use
- Traveler behavior impacts of VOTT across many choices

### **Computational performance:**

- Fully agent-based
- Integration with external optimization solvers (CPLEX, Gurobi, GLPK)
- High-performance C++ codebase
- Large-scale models with **100% of agents**
- 4-6 hr runtime for up to 10 million agents
- Cross-platform implementation can run on Linux HPC clusters



## Inputs for Population, Vehicles, and Land Use



4502

HYBRID ELECTRIC VEHICLE PLUG IN HYBRID ELECTRIC VEHICL

### **Detailed Inputs for Network and Mode Choice Modeling**

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rson Park CTA Statio

969.7 2.369.8

1 576.4 1 222.8 2 799.2



### Behavior Models Example: Activity Time-of-day and Duration Choice Models Allow Travelers to Respond to Changing Traffic Conditions and Opportunities

- Model jointly estimated for start time and duration
- Significant copula parameters: joint model valid
- Implemented as a parameterized choice
- Sensitive to key scenario parameters i.e. travel times and variability, activity pressure, etc.



Flexible, endogenous timing of all activities in the model, that is responsive to network conditions, captures realistic choice behavior...

### Behavioral Models Example: Mode Choice Specification to Capture Multimodal Decisions and New Mobility Options

- Updated ADAPTS/POLARIS mode choice model to include TNC: ٠
  - Leveraged benefits of large household travel survey
  - Combined with smaller, choice-based sample
- Identified and addressed differences between survey datasets ٠
- Constructed full multi-modal options using POLARIS router ٠

Conv.

Automated

(Cross)-Nested choice structure allows significant flexibility in modal substitution patterns



#### Key model results:

Waiting more burdensome than traveling Taxi has high value, followed by drive Rail has low value due to significant in-vehicle multi-tasking

		VOT by HH Income (\$)			
Mode	travel component	5000	30000	75000	120000
Drive	time in motion	\$15.36	\$18.59	\$20.24	\$21.09
Drive	parking "vot"	\$66.66	\$80.68	\$87.85	\$91.53
Taxi	time in motion	\$59.37	\$71.86	\$78.25	\$81.53
RailDrv	IVTT + Ac/Eg	\$3.27	\$3.96	\$4.31	\$4.49
RailDrv	Waiting time	\$5.04	\$6.10	\$6.64	\$6.92
RailWlk	IVTT + Ac/Eg	\$2.53	\$3.06	\$3.33	\$3.47
RailWlk	Waiting time	\$3.99	\$4.83	\$5.26	\$5.48
XitDrv	total time (IV,Ac/Eg,Wait)	\$1.70	\$2.06	\$2.25	\$2.34
XitWlk	IVTT + Ac/Eg	\$11.04	\$13.36	\$14.55	\$15.16
XitWlk	Waiting time	\$9.16	\$11.08	\$12.07	\$12.57

#### TNC / auto access to transit

Explore impact of ride-pooling, automation, vehicle sharing, micro-mobility etc. on mode choice

## Data

- Chicago Metropolitan Agency for Planning (CMAP) Travel Tracker Survey conducted on 2018-19.
  - Including approximately 14,000 households' activity and travel records for 24 hours.
- Google Maps Direction API including travel time for Transit, Walk and Bike modes
- POLARIS simulated data including travel time and costs for Auto and park & ride modes.









# **Telecommuting Model Development**

- Data source
  - Travel Tracker Survey conducted by the Chicago Metropolitan Agency for Planning (CMAP)
  - Includes complete travel information of 10,500 households who were asked to report their travel diary for one or two randomly assigned days
  - Information collected
    - Socio demographics (e.g., age, gender, income, etc.)
    - Household features (e.g., number of vehicles, residential location, etc.)
    - Trip-related characteristics (mode, time-ofday, trip duration, etc.)
    - Activity-related features (e.g., activity type and duration, location, etc.)



Distribution of telecommuting frequency in the sample

## **Telecommuting Model Development**

- A set of land-use and built-environment measures is calculated at the level of census tracts based on the available information about individuals' residential and work locations.
- A Zero-inflated hierarchical ordered probit model with correlated errors estimated telecommuting adoption and frequency.



Distribution of derived built-environment factors in Chicago Metropolitan Area

# Telecommuting Model Estimation

- Telecommuting adoption and frequency model suggests
  - occupation type also plays an important role in both participation and frequency level.
  - education and income level significantly affect both telecommuting participation and the frequency level.
  - flexibility of work schedule increases the probability of both telecommuting participation and frequency.
  - importance of trip-related and land-use variables on telecommuting choice:
    - travel time and distance to workplace
    - population density
    - employment density

Estimation Results of zero-inflated hierarchical ordered probit model with correlated errors.

Variables	Parameter	t-Stat
Participation equation (Potential of Telecommuti	ng Model):	
Constant	-0.98***	-5.33
Gender: male	0.26	3.01
Income: low	-0.64***	-5.64
Education: low	-0.67***	-6.03
Trip distance: high	0.22*	1.75
HH worker	0.18***	3.04
Work flexibility	0.89***	6.81
Occupation: transportation	-0.24	-1.65
Occupation: management	-0.61	-1.82
Occupation: health	-0.38***	-3.30
Employment density: high	0.34***	3.00
Population density	-0.07***	-3.46
Activity equation (Level of Telecommuting Model		
Constant	-0.62***	-3.01
Income: med	0.49	6.03
Age: 35–55	0.20***	3.31
Education: graduate	0.31	4.48
Trip duration	0.23***	3.06
HH vehicle	0.14***	4.15
Work flexibility	0.82***	8.49
Occupation: government	-0.23**	-2.19
Occupation: communication	0.31**	2.27
Occupation: manufacturing	-0.16	-1.65
Employment density: low	-0.22***	-3.10
Threshold variables:		
Work duration	0.03***	2.89
Vehicle availability	-0.11	-1.72
HH vehicle: high	0.26***	3.22
Threshold constants:		
$\theta_1$	-1.60***	-10.86
$\theta_2$	-0.47***	-4.08
$\theta_3$	0.43***	4.64
Correlation coefficient:		
ρ	0.28*	1.91
log-likelihood at convergence	-3206.05	

Note: \*\*\*, \*\*, \* indicate significance at 1%, 5%, and 10% level.

### **Implementation in POLARIS**

- The results endorse the fact that telecommuting policy has the potential to reduce network congestion and vehicular emissions specifically during rush hours
- As a sustainable transportation policy, Telecommuting can alleviate network congestion by reducing the total daily VMT and VHT by up to 2.4% and 4.15%
- Telecommuting policy also has the potential to reduce GHG and PM2.5 emissions by up to 2.65% and 2.95%

#### Changes in Emissions and Fuel Consumption in Telecommuting Scenarios

Emissions	Flex–25 vs. base scenario	Flex–50 vs. base scenario
Average Daily GHG (US ton)	-329.5 (-0.3%)	-766.3 (-0.7%)
Average Daily PM <sub>2.5</sub> (lb)	-164.2 (-0.05%)	-367.5 (-1.1%)
Average Daily Fuel Consumption (Million Gallons)	-0.03 (-0.3%)	-0.08 (-0.8%)



## Long-Distance Travel Overview

- Purpose
  - Critical to understand what happens when travelers replace their average day trip with long-distance trips
  - Simulation of long-distance travel model is warranted
    - To represent travel demand in a more behaviorally realistic way
    - To provide solutions for the travel demand increment due to airport expansions
- Presents long-distance trip generation model and appropriate behavioral models representing the choice of airport access/egress mode including the high-speed rail
- Implements long-distance travel models within POLARIS and establishes linkages with activity-based models

# Long-distance Travel Model Development

### Data source

- Multi-wave survey of long-distance travel behavior for state of Illinois
- Responses: 1791 households; 2,225 individuals; 3012 long-distance trips
- Information collected:
  - Socio-demographics and Household features (e.g., housing income, vehicle ownership, etc.)
  - Details about all long-distance trips of the individual within a determined period (e.g., number of longdistance trips, start day and time, main mode of the trip, access/egress mode if applicable, party size, origin and destination, trip purpose, etc.)
- Long-distance travel models developed (for <u>business trips</u> and <u>non-business</u>)
  - Trip frequency models
  - Start time choice model
  - Access mode choice model
  - Egress mode choice model

# Implementation in POLARIS

- At first, long-distance (LD) trip frequency models generate trip decisions and number of trips using zero-inflated negative binomial model
- For trips = 0, activity generation model generates average day trips and its attributes
- No. of long-distance trips ≥ 1 triggers the implementation of other trip attributes
- LD travel module replaces daily activity generation model, and generates long-distance trip attributes
- For each trip,
  - start time model generates time-of-day of the long-distance trip start time using multinomial logit model
  - destination is generated using nested logit model
  - finally, runs mode choice processes using multinomial logit model for access, main and egress modes



# Micromobility

- E-scooters/e-bike/shared-bike provide people more options for short-distance trips
- Supplement transit services by providing more access/egress alternatives
- Carbon-free mobility contributes to sustainable city development
- Purpose:
  - To better understand the role of shared micromobility in urban mobility
  - To explore how people adopt mcromobility
  - How frequently they use them
- Presents micromobility adoption choice model
- Implements the adoption behavior within POLARIS
- Run operational scenarios to understand the effect of future micromobility usage 18

## Data

- E-Scooter Adoption Model Survey: 603 respondents
- Collected information
  - Demographics
  - E-scooter adoption behavior (frequency of use) based on e-scooter pilot program participation
  - Reasons for e-scooter use
  - Daily travel mode choice (mode and usage frequency)
  - Residential location
- Additional data: EPA Smart Location Database, E-scooter API for trip service characteristics

## Model

### • Differentiate users

- Potential users (access to e-scooters but have not used it)
- Non-users (no access to e-scooters)
- Four level of usage considered for potential users
  - Do not use
  - Few times during pilot (3 months)
  - Few times per month
  - Few times per week
- Zero-inflated ordered probit model
  - Bi-level approach, dealing with excessive zero counts
  - Jointly investigates intention to adopt e-scooters and associated usage frequency



## Scenarios

- 5 operational scenarios of e-scooter deployment were studied in *Bloomington*
- Demand for e-scooters depended on e-scooter availability by time of day
- Since some short auto trips can be replaced by e-scooters, VMT savings up to 8% are observed
- Shift away from walk also helps lower overall **PHT up to 11%**

E-scooter fleet size	Trips Made	% ΔνΜτ	% ΔΡΗΤ
Base   500	11,549	-	-
5x   2,500	14,166	-2.8%	-4.1%
10x   5,000	15,382	-4.5%	-5.6%
25x   12,500	17,030	-5.9%	-8.9%
50x   25,000	18,343	-8.3%	-11.1%

VMT – Vehicle Miles Traveled PHT – Person Hours Traveled

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